

Transparent Interaction of SCADA Systems Developed over Different Technologies

Ioan UNGUREAN, Nicoleta Cristina GAITAN, Vasile Gheorghita GAITAN

ioanu@eed.usv.ro, cristinag@eed.usv.ro, galtan@eed.usv.ro

OUTLINE

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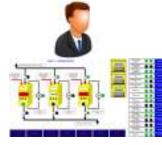
1. INTRODUCTION (1)

SCADASystems

- SCADA Supervisory Control and Data Acquisition systems;
- Hardware/software systems that allow:
 - Data acquisition from sensors or field devices used in the monitoring and control of industrial process;
 - Transmission of commands/instructions to the remote field devices or actuators.

1. INTRODUCTION (2)

- ▶ The main elements of an **SCADA** systems are:
 - The human operator;
 - HMI Human Machine Interface;
 - MTU Master Terminal Unit;
 - RTU Remote Terminal Unit.







1. INTRODUCTION (3)

- The most-used middleware technologies are
 - based on OPC specifications (OPC DA, OPC.NET, OPC UA)



 based on CORBA (Common Object Request Broker Architecture) standard



based on DDS (Data Distribution Service) protocol;



based on AMQP (Advanced Message Queuing Protocol).



2. MIDDLEWARE TECHNOLGIES FOR SCADA SYTEMS (1)

- OPC specifications are developed and sustained by OPC Foundation.
- Currently, the OPC Foundation provides three middleware architectures, namely:
 - Classic OPC DA (based on DCOM technology from Microsoft),
 - OPC .NET initially called Xi Express interface (based on Windows Communication Foundation from Microsoft)
 - OPC UA -Unified Architecture (based on SOAP and Web services).



2. MIDDLEWARE TECHNOLGIES FOR SCADA SYTEMS (2)

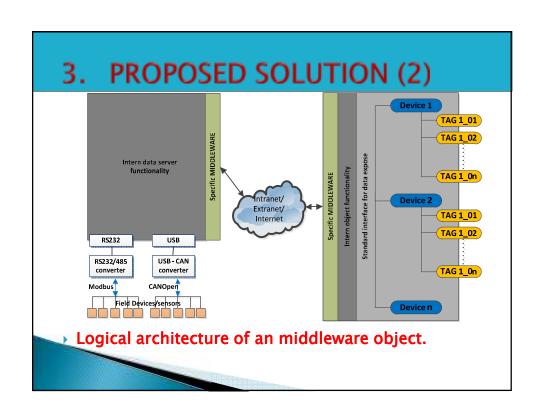
- CORBA (Common Object Request Broker Architecture) is a middleware standard based on the client/server paradigm to distribute data between heterogeneous applications in terms of programming language and operating system used.
- For real-time distribution, there are defined RT-CORBA specifications that can achieve a deterministic access to shared resources
- CORBA is still used for data distribution in LHC Control Systems.

2. MIDDLEWARE TECHNOLGIES FOR SCADA SYTEMS (3)

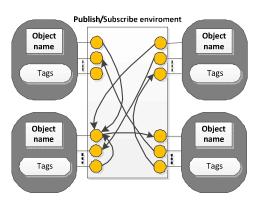
- DDS (Data Distribution Service for Real-Time Systems) is a middleware standard based on the publish/subscribe paradigm to distribute data between heterogeneous applications.
- An important feature of this protocol is that it has facilities for implementing QoS (Quality of Service) parameters in order to achieve real-time performance.
- Due to real-time facilities, this protocol is used in critical systems in the detriment of OPC based solutions.

3. PROPOSED SOLUTION (1)

- It is proposed a framework, which will further be named MIOF (Middleware Inter-Operability Framework).
- MIOF is based on middleware objects and connections between these objects.
- Each object encapsulates a specific functionality depending on the middleware on which is based.
- Each middleware object has a set of parameters and a set of tags or data members (which behaves like input/output points).



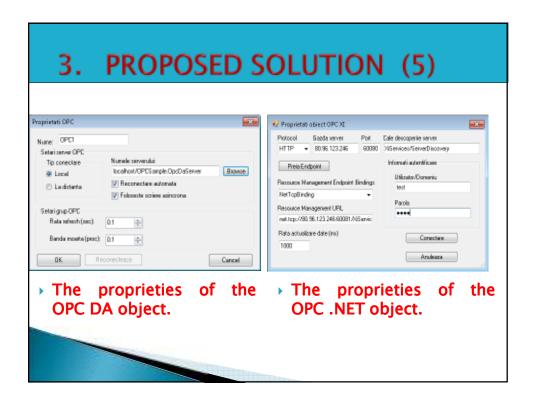
PROPOSED SOLUTION (3)



The interconnection way of middleware objects.

3. PROPOSED SOLUTION (4)

- At this moment, there are implemented middleware objects for the:
 - OPC DA;
 - OPC .NET;
 - OPC UA;
 - TAO an implementation of CORBA;
 - OpenDDS implementation of the DDS standard.



4. FUTURE WORK

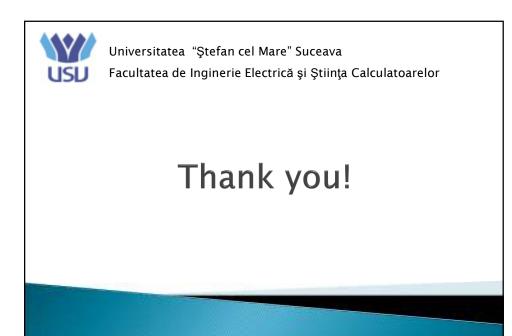
- Can be developed objects that will take the address space of the MIOF environment, and they can distribute it through a specific middleware;
- Can be created OPC UA, OPC. NET and OPC UA objects that work as servers, and they expose the address space of the MIOF environment.

5. CONCLUSIONS

- We presented a solution for interoperability of SCADA system developed over different technologies in terms of middleware systems.
- The proposed solution operates on the publish/subscribe paradigm.
- We can easily introduce new objects that can retrieve data through a specific middleware or other methods such as service-oriented applications.

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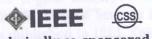
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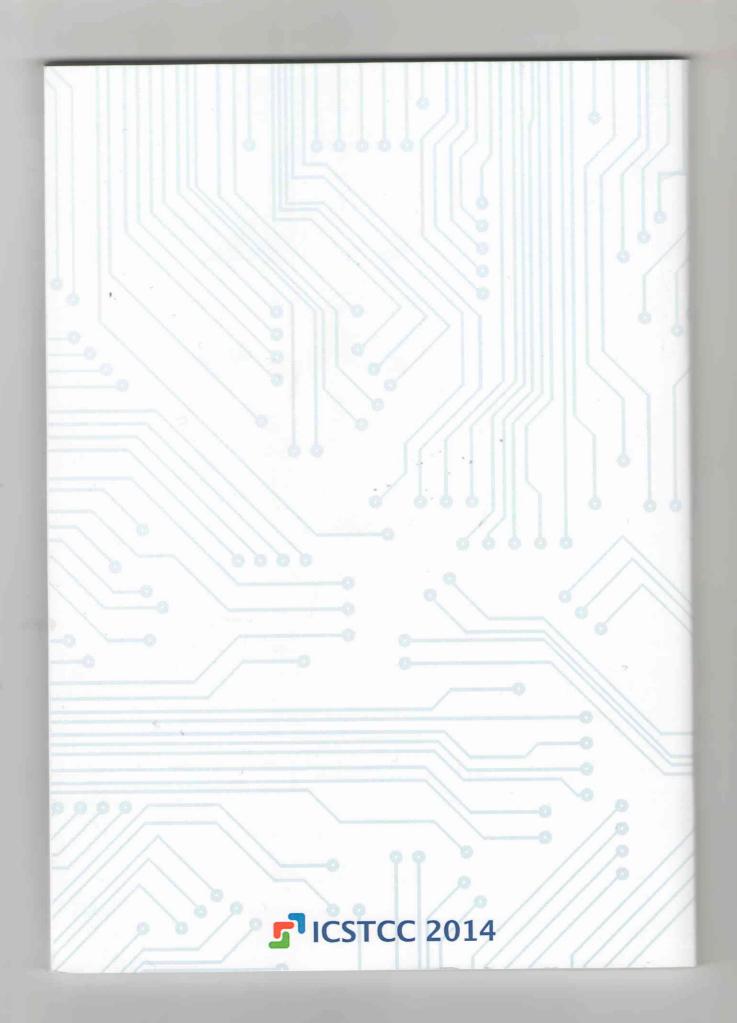
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